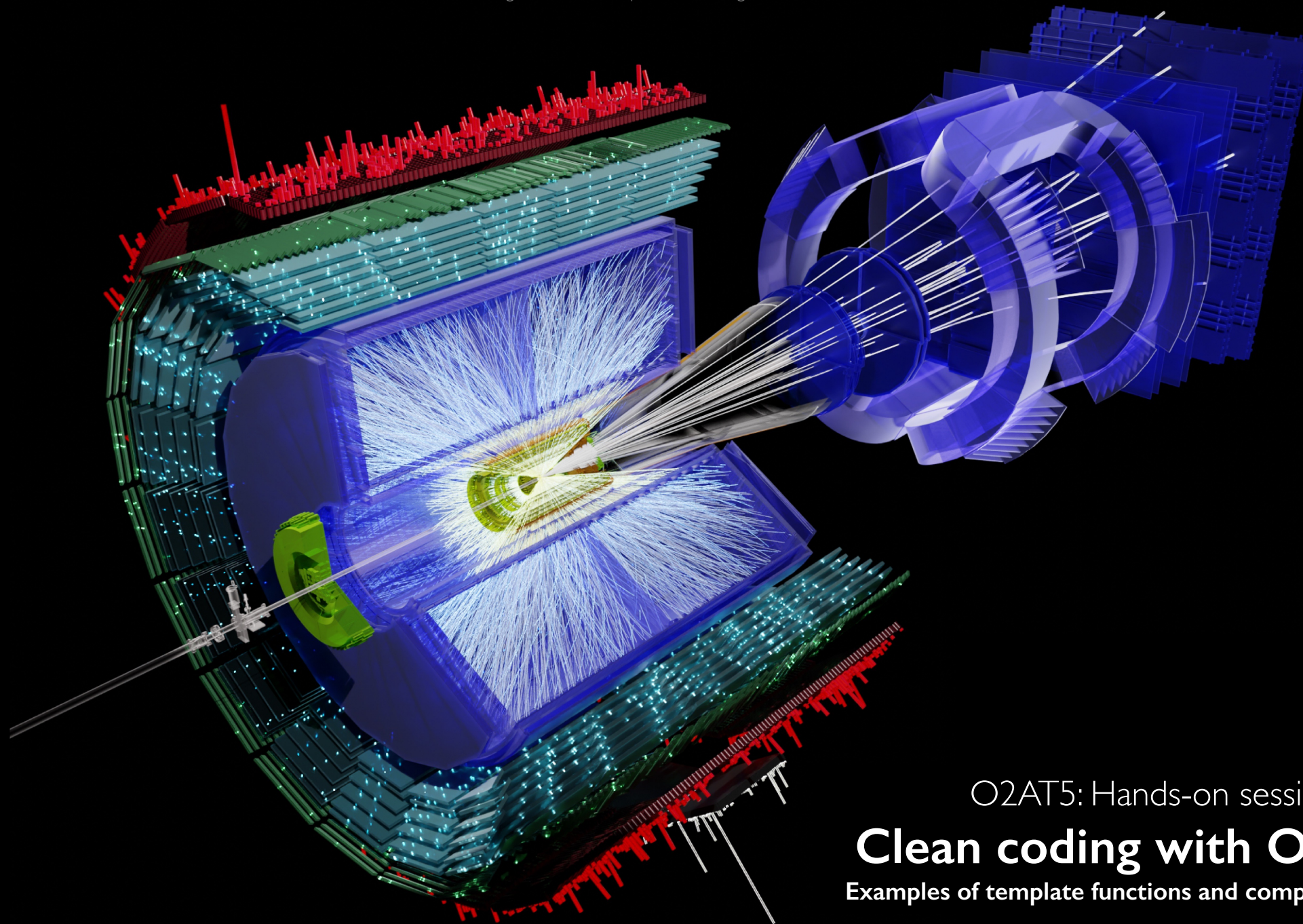




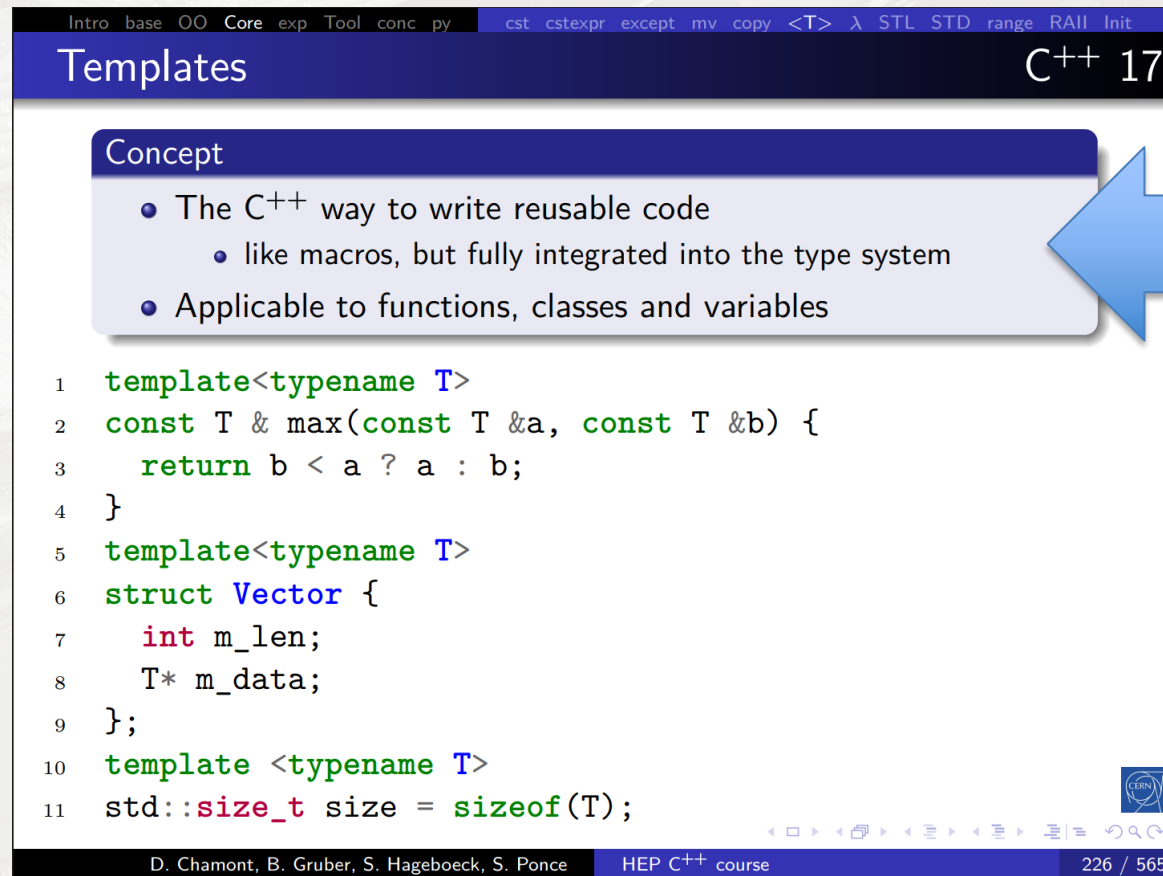
O2AT5: Hands-on session IV

Clean coding with O2Physics

Examples of template functions and compile time directives

Further resources on modern C++ coding:

[13th HEP C++ Course and Hands-on Training - Advanced C++](#)



The screenshot shows a presentation slide titled "Templates" for "C++ 17". It includes a navigation bar at the top with various topics like "Intro", "base", "OO", "Core", "exp", "Tool", "conc", "py", "cst", "cstexpr", "except", "mv", "copy", "<T>", "λ", "STL", "STD", "range", "RAII", and "Init". A blue arrow points from the right towards a "Concept" box. The "Concept" box contains a bulleted list. Below it, there is C++ code for a max function, a Vector struct, and a size variable. The footer of the slide lists the authors: D. Chamont, B. Gruber, S. Hageboeck, S. Ponce, and identifies it as the "HEP C++ course" slide 226 of 565.

Concept

- The C++ way to write reusable code
 - like macros, but fully integrated into the type system
- Applicable to functions, classes and variables

```
1 template<typename T>
2 const T & max(const T &a, const T &b) {
3     return b < a ? a : b;
4 }
5 template<typename T>
6 struct Vector {
7     int m_len;
8     T* m_data;
9 };
10 template <typename T>
11 std::size_t size = sizeof(T);
```

D. Chamont, B. Gruber, S. Hageboeck, S. Ponce HEP C++ course 226 / 565

- If you'd like to learn C++ from the basics to templates and beyond, please take a look!

Data for this exercise

- Let's use the same data you downloaded for the first and second hands-on exercises!
- These correspond to real data ([dropbox](#), [cernbox](#)) and simulation ([dropbox](#), [cernbox](#)) for Pb-Pb 2023
- We'll basically take the task you had at the end of the second hands-on and clear it up a little such that it is more flexible and does not involve any code documentation

The starting point: the task to calculate efficiencies

```
struct myExampleTask {  
    // Histogram registry: an object to hold your histograms  
    HistogramRegistry histos{"histos", {},  
    OutputObjHandlingPolicy::AnalysisObject};  
  
    void processReco(aod::Collision const& collision, myFiltered const& tracks,  
    aod::McParticles const&)  
    {  
        // Huge block of code  
    }  
    PROCESS_SWITCH(myExampleTask, processReco, "process reconstructed  
information", true);  
  
    void processSim(aod::McCollision const& mcCollision,  
    soa::SmallGroups<soa::Join<aod::McCollisionLabels, aod::Collisions>> const&  
    collisions, aod::McParticles const& mcParticles, myFiltered const& tracks)  
    {  
        // Huge block of code  
    }  
    PROCESS_SWITCH(myExampleTask, processSim, "process pure simulation  
information", true);  
};
```

- Starting point: the previous code!
- The good old:

myExampleTask.cxx
+
Changes ([link](#))

- A common problem: this task can actually only run on MC, because a subscription to McParticles is present!
- What if we would like to use the same task in real data?

The starting point: the task to calculate efficiencies

```
struct myExampleTask {  
    // Boilerplate stuff goes here  
  
    void processRecoInData(aod::Collision const& collision, [tracks])  
    {  
        // Huge block of code  
    }  
    PROCESS_SWITCH(myExampleTask, processRecoInData, "process reco in data", true);  
  
    void processRecoInSim(aod::Collision const& collision, [tracks], [McParticles])  
    {  
        // Huge block of code  
    }  
    PROCESS_SWITCH(myExampleTask, processRecoInSim, "process reco in MC", false);  
  
    void processSim(aod::McCollision const& mcCollision,  
        soa::SmallGroups<soa::Join<aod::McCollisionLabels, aod::Collisions>> const&  
        collisions, aod::McParticles const& mcParticles, myFiltered const& tracks)  
    {  
        // Huge block of code  
    }  
    PROCESS_SWITCH(myExampleTask, processSim, "process pure sim", false);  
};
```

- Starting point: the previous code!
- The good old:

myExampleTask.cxx
+
Changes ([link](#))

- A common problem: this task can actually only run on MC, because a subscription to McParticles is present!
- What if we would like to use the same task in real data? Yet another process function...

The starting point: the task to calculate efficiencies

```
struct myExampleTask {  
    // Boilerplate stuff goes here  
  
    void processRecoInData(aod::Collision const& collision, [tracks])  
    {  
        // Huge block of code  
    }  
    PROCESS_SWITCH(myExampleTask, processRecoInData, true);  
  
    void processRecoInSim(aod::Collision const& collision, [particles])  
    {  
        // Huge block of code  
    }  
    PROCESS_SWITCH(myExampleTask, processRecoInSim, "process reco in MC", false);  
  
    void processSim(aod::McCollision const& mcCollision,  
        soa::SmallGroups<soa::Join<aod::McCollisionLabels, aod::Collisions>> const&  
        collisions, aod::McParticles const& mcParticles, myFiltered const& tracks)  
    {  
        // Huge block of code  
    }  
    PROCESS_SWITCH(myExampleTask, processSim, "process pure sim", false);  
};
```

These huge blocks of code
will have common parts!
Dangerous and inconvenient

- Starting point: the previous code!
- The good old:

myExampleTask.cxx
+
Changes ([link](#))

- A common problem: this task can actually only run on MC, because a subscription to McParticles is present!
- What if we would like to use the same task in real data? Yet another process function...

This can be handled conveniently in modern C++ with template functions a series of tricks!

What do we want to achieve?

```
struct myExampleTask {  
    // Boilerplate stuff goes here  
  
    void processStuff(arguments){  
        // do data stuff here  
  
        // do MC stuff here but only if it's MC  
    }  
  
    void processRecoInData(aod::Collision const& collision, [tracks])  
    {  
        processStuff(collision, tracks); // simple data tracks  
    }  
    PROCESS_SWITCH(myExampleTask, processRecoInData, "process reco in data", true);  
  
    void processRecoInSim(aod::Collision const& collision, [tracks], [McParticles])  
    {  
        processStuff(collision, tracks); // these tracks will be labeled!  
    }  
    PROCESS_SWITCH(myExampleTask, processRecoInSim, "process reco in MC", false);  
};
```

- Could we make the processing such that 'process' functions define the interface to O2Physics but serve only as an entry point to a 'processStuff' function that adapts depending on complex compile-time conditions?
- For instance, in the second process function the tracks will contain a "mcParticleId", but not in the first. How can we deal with this and detect, inside processStuff, if the MC part is to be done or not?

```

using myCompleteTracksMC = soa::Join<aod::Tracks, aod::TracksExtra, aod::TracksDCA, aod::McTrackLabels>;
using myCompleteTracks = soa::Join<aod::Tracks, aod::TracksExtra, aod::TracksDCA>;
using myFilteredTracksMC = soa::Filtered<myCompleteTracksMC>;
using myFilteredTracks = soa::Filtered<myCompleteTracks>;

```

```

template <typename TCollision, typename TTracks>
void processStuff(TCollision const& collision, TTracks const& tracks) {
    histos.fill(HIST("eventCounter"), 0.5f);
    for (const auto& track : tracks) {
        if( track.tpcNClsCrossedRows() < minTPCCrossedRows ) continue; //badly tracked
        histos.fill(HIST("etaHistogram"), track.eta());
        histos.fill(HIST("ptHistogram"), track.pt());

        // this part only done if dealing with MC
        if constexpr (requires { track.has_mcParticle(); }) { // does the getter exist?
            if(track.has_mcParticle()){ // is the return 'true'? -> N.B. different question!
                auto mcParticle = track.mcParticle();
                histos.fill(HIST("ptResolution"), track.pt(), track.pt() - mcParticle.pt());
                if(mcParticle.isPhysicalPrimary() && fabs(mcParticle.y())<0.5){
                    if(abs(mcParticle.pdgCode())==kPiPlus) histos.fill(HIST("ptHistogramPion"), mcParticle.pt());
                    if(abs(mcParticle.pdgCode())==kKPlus) histos.fill(HIST("ptHistogramKaon"), mcParticle.pt());
                    if(abs(mcParticle.pdgCode())==kProton) histos.fill(HIST("ptHistogramProton"), mcParticle.pt());
                }
            }
        }
    }
}

void processRecoInData(aod::Collision const& collision, myFilteredTracks const& tracks)
{
    processStuff(collision, tracks);
}
PROCESS_SWITCH(myExampleTask, processRecoInData, "process reco in real data", true);

void processRecoInSim(aod::Collision const& collision, myFilteredTracksMC const& tracks, aod::McParticles
const&)
{
    processStuff(collision, tracks);
}
PROCESS_SWITCH(myExampleTask, processRecoInSim, "process reco in mc data", false);

```

Yes, we can: using
template functions and
compile time directives

There are plenty of elements
in this solution: let's break it
down...


```

using myCompleteTracksMC = soa::Join<aod::Tracks, aod::TracksExtra, aod::TracksDCA, aod::McTrackLabels>;
using myCompleteTracks = soa::Join<aod::Tracks, aod::TracksExtra, aod::TracksDCA>;
using myFilteredTracksMC = soa::Filtered<myCompleteTracksMC>;
using myFilteredTracks = soa::Filtered<myCompleteTracks>;

```

```

template <typename TCollision, typename TTracks>
void processStuff(TCollision const& collision, TTracks const& tracks) {
    histos.fill(HIST("eventCounter"), 0.5f);
    for (const auto& track : tracks) {
        if( track.tpcNclsCrossedRows() < minTPCCrossedRows ) continue; //badly tracked
        histos.fill(HIST("etaHistogram"), track.eta());
        histos.fill(HIST("ptHistogram"), track.pt());

        // this part only done if dealing with MC
        if constexpr (requires { track.has_mcParticle(); }) { // does the getter exist?
            if(track.has_mcParticle()){ // is the return 'true'? -> N.B. different question!
                auto mcParticle = track.mcParticle();
                histos.fill(HIST("ptResolution"), track.pt(), track.pt() - mcParticle.pt());
                if(mcParticle.isPhysicalPrimary() && fabs(mcParticle.y())<0.5){
                    if(abs(mcParticle.pdgCode())==kPiPlus) histos.fill(HIST("ptHistogramPion"), mcParticle.pt());
                    if(abs(mcParticle.pdgCode())==kKPlus) histos.fill(HIST("ptHistogramKaon"), mcParticle.pt());
                    if(abs(mcParticle.pdgCode())==kProton) histos.fill(HIST("ptHistogramProton"), mcParticle.pt());
                }
            }
        }
    }
}

void processRecoInData(aod::Collision const& collision, myFilteredTracks const& tracks)
{
    processStuff(collision, tracks);
}
PROCESS_SWITCH(myExampleTask, processRecoInData, "process reco in real data", true);

void processRecoInSim(aod::Collision const& collision, myFilteredTracksMC const& tracks, aod::McParticles
const&)
{
    processStuff(collision, tracks);
}
PROCESS_SWITCH(myExampleTask, processRecoInSim, "process reco in mc data", false);

```

Yes, we can: using
template functions and
compile time directives

Function with template arguments: in
each context in which the function is
used, the compiler checks arguments and
specializes the processStuff function

```
using myCompleteTracksMC = soa::Join<aod::Tracks, aod::TracksExtra, aod::TracksDCA, aod::McTrackLabels>;
using myCompleteTracks = soa::Join<aod::Tracks, aod::TracksExtra, aod::TracksDCA>;
using myFilteredTracksMC = soa::Filtered<myCompleteTracksMC>;
using myFilteredTracks = soa::Filtered<myCompleteTracks>;
```

```
template <typename TCollision, typename TTracks>
void processStuff(TCollision const& collision, TTracks const& tracks) {
    histos.fill(HIST("eventCounter"), 0.5f);
    for (const auto& track : tracks) {
        if( track.tpcNclsCrossedRows() < minTPCCrossedRows ) continue; //badly tracked
        histos.fill(HIST("etaHistogram"), track.eta());
        histos.fill(HIST("ptHistogram"), track.pt());

        // this part only done if dealing with MC
        if constexpr (requires { track.has_mcParticle(); }) { // does the getter exist?
            if(track.has_mcParticle()){ // is the return 'true'? -> N.B. different question!
                auto mcParticle = track.mcParticle();
                histos.fill(HIST("ptResolution"), track.pt(), track.pt() - mcParticle.pt());
                if(mcParticle.isPhysicalPrimary() && fabs(mcParticle.y())<0.5){
                    if(abs(mcParticle.pdgCode())==kPiPlus) histos.fill(HIST("ptHistogramPion"), mcParticle.pt());
                    if(abs(mcParticle.pdgCode())==kKPlus) histos.fill(HIST("ptHistogramKaon"), mcParticle.pt());
                    if(abs(mcParticle.pdgCode())==kProton) histos.fill(HIST("ptHistogramProton"), mcParticle.pt());
                }
            }
        }
    }
}
```

```
void processRecoInData(aod::Collision const& collision, myFilteredTracks const& tracks)
{
    processStuff(collision, tracks);
}
PROCESS_SWITCH(myExampleTask, processRecoInData, "process reco in real data", true);
```

```
void processRecoInSim(aod::Collision const& collision, myFilteredTracksMC const& tracks, aod::Collision const&)
{
    processStuff(collision, tracks);
}
PROCESS_SWITCH(myExampleTask, processRecoInSim, "process reco in mc data", false);
```

Yes, we can: using
template functions and
compile time directives

Function with template arguments: in each context in which the function is used, the compiler checks arguments and specializes the processStuff function

The two calls are different! In one case, I have access to mcParticle label getters, but in the other one I do not!



```
using myCompleteTracksMC = soa::Join<aod::Tracks, aod::TracksExtra, aod::TracksDCA, aod::McTrackLabels>;
using myCompleteTracks = soa::Join<aod::Tracks, aod::TracksExtra, aod::TracksDCA>;
using myFilteredTracksMC = soa::Filtered<myCompleteTracksMC>;
using myFilteredTracks = soa::Filtered<myCompleteTracks>;
```

```
template <typename TCollision, typename TTracks>
void processStuff(TCollision const& collision, TTracks const& tracks) {
    histos.fill(HIST("eventCounter"), 0.5f);
    for (const auto& track : tracks) {
        if( track.tpcNclsCrossedRows() < minTPCCrossedRows ) continue; //badly tracked
        histos.fill(HIST("etaHistogram"), track.eta());
        histos.fill(HIST("ptHistogram"), track.pt());

        // this part only done if dealing with MC
        if constexpr (requires { track.has_mcParticle(); }) { // does the getter exist?
            if(track.has_mcParticle()){ // is the return 'true'? -> N.B. different question!
                auto mcParticle = track.mcParticle();
                histos.fill(HIST("ptResolution"), track.pt(), track.pt() - mcParticle.pt());
                if(mcParticle.isPhysicalPrimary() && fabs(mcParticle.y())<0.5){
                    if(abs(mcParticle.pdgCode())==kPiPlus) histos.fill(HIST("ptHistogramPion"), mcParticle.pt());
                    if(abs(mcParticle.pdgCode())==kKPlus) histos.fill(HIST("ptHistogramKaon"), mcParticle.pt());
                    if(abs(mcParticle.pdgCode())==kProton) histos.fill(HIST("ptHistogramProton"), mcParticle.pt());
                }
            }
        }
    }
}
```

```
void processRecoInData(aod::Collision const& collision, myFilteredTracks const& tracks)
{
    processStuff(collision, tracks);
}
PROCESS_SWITCH(myExampleTask, processRecoInData, "process reco in real data", true);
```

```
void processRecoInSim(aod::Collision const& collision, myFilteredTracksMC const& tracks, aod::Collision const&)
{
    processStuff(collision, tracks);
}
PROCESS_SWITCH(myExampleTask, processRecoInSim, "process reco in mc data", false);
```

Yes, we can: using template functions and compile time directives

Function with template arguments: in each context in which the function is used, the compiler checks arguments and specializes the processStuff function

The two calls are different! In one case, I have access to mcParticle label getters, but in the other one I do not!

The processStuff function checks if I have the getter functionality at compile time




```
using myCompleteTracksMC = soa::Join<aod::Tracks, aod::TracksExtra, aod::TracksDCA, aod::McTrackLabels>;
using myCompleteTracks = soa::Join<aod::Tracks, aod::TracksExtra, aod::TracksDCA>;
using myFilteredTracksMC = soa::Filtered<myCompleteTracksMC>;
using myFilteredTracks = soa::Filtered<myCompleteTracks>;
```

```
template <typename TCollision, typename TTracks>
void processStuff(TCollision const& collision, TTracks const& tracks) {
    histos.fill(HIST("eventCounter"), 0.5f);
    for (const auto& track : tracks) {
        if( track.tpcNclsCrossedRows() < minTPCCrossedRows ) continue; //badly tracked
        histos.fill(HIST("etaHistogram"), track.eta());
        histos.fill(HIST("ptHistogram"), track.pt());
```

```
// this part only done if dealing with MC
```

```
if constexpr (requires { track.has_mcParticle(); }) { // does the getter exist?
    if(track.has_mcParticle()){ // is the return 'true'? -> N.B. different question!
```

```
        auto mcParticle = track.mcParticle();
        histos.fill(HIST("ptResolution"), track.pt(), track.pt() - mcParticle.pt());
        if(mcParticle.isPhysicalPrimary() && fabs(mcParticle.y())<0.5){
            if(abs(mcParticle.pdgCode())==kPiPlus) histos.fill(HIST("ptHistogramPion"), mcParticle.pt());
            if(abs(mcParticle.pdgCode())==kKPlus) histos.fill(HIST("ptHistogramKaon"), mcParticle.pt());
            if(abs(mcParticle.pdgCode())==kProton) histos.fill(HIST("ptHistogramProton"), mcParticle.pt());
        }
    }
}
```

Yes, we can: using
template functions and
compile time directives

Asking if the getter exists $\neq$ getter returns true

Final effects:

- The compiled executable will technically contain two versions of 'processStuff', but **you will need to edit only one block of code!**
- 'if constexpr' is checked at compile time: executes faster than runtime checks because the decision is already done
- Multiple other tricks exist for compile-time decisionmaking

Function with template arguments: in each context in which the function is used, the compiler checks arguments and specializes the processStuff function

The two calls are different! In one case, I have access to mcParticle label getters, but in the other one I do not!

The processStuff function checks if I have the getter functionality at compile time



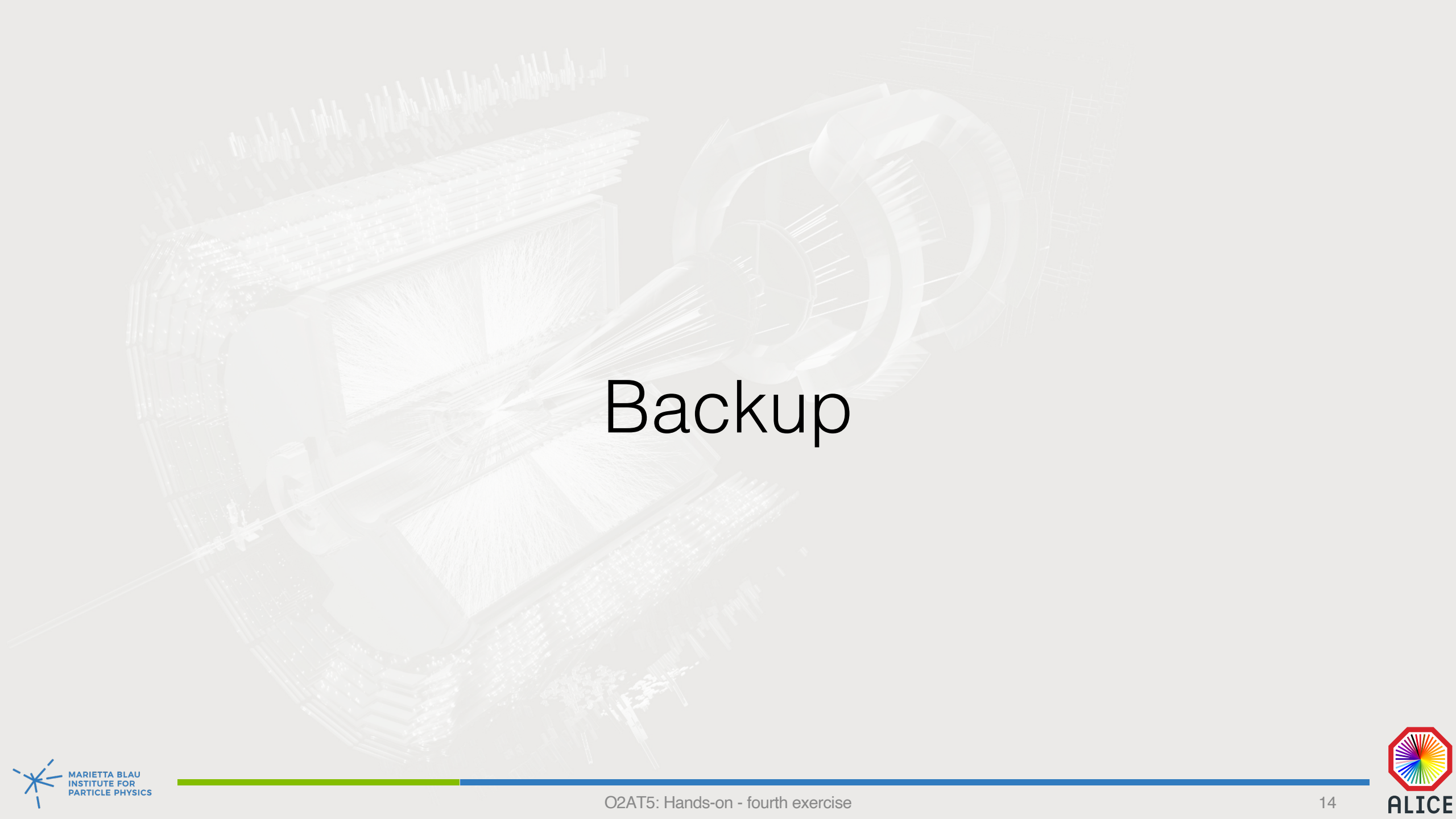
Compile-time arguments: example

```
template <bool fillResolution = true, typename TCollision, typename TTracks>
void processStuff(TCollision const& collision, TTracks const& tracks) {
    histos.fill(HIST("eventCounter"), 0.5f);
    for (const auto& track : tracks) {
        if( track.tpcNclsCrossedRows() < minTPCCrossedRows ) continue; //badly tracked
        histos.fill(HIST("etaHistogram"), track.eta());
        histos.fill(HIST("ptHistogram"), track.pt());

        // this part only done if dealing with MC
        if constexpr (requires { track.has_mcParticle(); }) { // does the getter exist?
            if(track.has_mcParticle()){ // is the return 'true'? -> N.B. different question!
                auto mcParticle = track.mcParticle();
                if constexpr (fillResolution){ // compile-time check
                    histos.fill(HIST("ptResolution"), track.pt(), track.pt() - mcParticle.pt());
                }
                if(mcParticle.isPhysicalPrimary() && fabs(mcParticle.y())<0.5){
                    if(abs(mcParticle.pdgCode())==kPiPlus) histos.fill(HIST("ptHistogramPion"), mcParticle.pt());
                    if(abs(mcParticle.pdgCode())==kKPlus) histos.fill(HIST("ptHistogramKaon"), mcParticle.pt());
                    if(abs(mcParticle.pdgCode())==kProton) histos.fill(HIST("ptHistogramProton"), mcParticle.pt());
                }
            }
        }
    }
}
```

- Another option is to define arguments such as a boolean for doing something specific
- In this case, one can now invoke processStuff<true>(collision, tracks)
- This might run faster (conditional checked at compile time and NOT at runtime)
- Drawback: the compiler will create two copies of the compiled function

The solution to this exercise can be found [here](#)



Backup



Surgical compilation: ninja to the rescue

- **If you have a compiled O2Physics installation** and just want to recompile one subdirectory or even one particular executable, this can be done using a tool called “ninja” – it will help you be faster!

- Go to your build directory using:

Bear in mind: different path needed for any non-standard installation path

```
cd ~/alice/sw/BUILD/O2Physics-latest/O2Physics
```

- Once in that directory, load the build environment doing: (important: you should not have called alienv before!)

```
direnv allow
```

- You can then rebuild only one specific subdirectory of O2Physics:

```
ninja <directory>/install # Example: ninja PWGCF/Tasks/install
```

- You can even rebuild only one single executable:

```
ninja stage/bin/<target> # Example: ninja stage/bin/o2-analysis-cf-correlations
```